Amendments to the Claims:

This listing of claims will replace all prior versions, and listings, of claims in the application:

Listing of Claims:

1. (Previously Presented) A method of reducing a blocking artifact appearing when coding a moving picture, comprising the steps of:

defining pixels, S_0 , S_1 , and S_2 centering around a block boundary;

obtaining a mode determination value to selectively determine a deblocking mode as a default mode or a DC offset mode in accordance with a degree of the blocking artifact;

obtaining frequency information of the surroundings of the block boundary for each pixel, using a 4-point kernel, if the default mode is determined;

adjusting a magnitude of a discontinuous component, belonging to the block boundary, to the minimum value of a magnitude of a discontinuous component, belonging to the surrounding of the block boundary, in a frequency domain, and applying said adjusting operation to a spatial domain; and

reducing the blocking artifact in a smooth region where there is little motion, such as a setting, if the DC offset mode is determined.

2. (Previously Presented) The method according to claim 1, wherein the obtaining through adjusting steps are performed in the default mode.

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- 3. (Previously Presented) The method according to claim 1, wherein a magnitude of the discontinuous component in the S_0 pixel is adjusted to a magnitude of the corresponding component in a second pixel, wherein the magnitude of the corresponding component in the second pixel is based on a smallest value of corresponding component magnitudes in the S_1 and S_2 pixels.
- 4. (Previously Presented) The method according to claim 3, wherein the adjusting step satisfies at least one of the following conditions:

$$v_{3}' = v_{3} - d$$
; and

$$v_{4}' = v_{4} + d$$
; where $d = CLIP (c_{2}(a_{3,0}' - a_{3,0})//c_{3}, 0, (v_{3} - v_{4})/2)*\delta(|a_{3,0}| \langle QP),$

$$a_{3,0}' = SIGN(a_{3,0})*MIN(|a_{3,0}|, |a_{3,1}|, |a_{3,2}|), \text{ wherein } v_{3} - v_{4}$$

are initial boundary pixel values, $v_3' - v_4'$ are adjusted boundary pixel values, $a_{3,0} - a_{3,2}$ are the discontinuous component of the discrete cosine transform coefficients of the S_0 , S_1 and S_2 pixels, c_2 and c_3 are DCT kernel coefficients and QP is a quantization parameter of a macroblock containing v_4 .

5. (Previously Presented) The method according to claim 3, wherein the S₁ and S₂ pixels are positioned within a block adjacent the block boundary.

- 6. (Previously Presented) The method according to claim 1, further comprising:

 determining a smoothness level of the plurality of pixels; and

 selecting one of the default mode and the DC offset mode based on the
 smoothness level, wherein the blocking artifact is reduced based on the selected mode.
- 7. (Previously Presented) The method according to claim 6, wherein the DC offset mode is selected when the following condition is satisfied: $(v_0 == v_1 \& \& v_1 == v_2 \& \& v_2 == v_3 \& \& v_4 == v_5 \& \& v_5 == v_6 \& \& v_6 == v_7)$, wherein $v_0 v_7$ are boundary pixel values.
- 8. (Previously Presented) The method according to claim 6, wherein in the DC offset mode is selected for a region of the motion picture where there is little motion.
- 9. (Original) The method according to claim 8, wherein the adjusting step prevents over-smoothing when the blocking artifact is not very serious and counts an effect of a quantization parameter.
- 10. (Previously Presented) The method according to claim 6, wherein the adjusting step in the DC offset mode satisfies at least one of the following conditions:

$$v_{3}' = v_{3} - d;$$

$$v_4' = v_4 + d;$$

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$$v_2' = v_2 - d_2;$$
 $v_5' = v_5 + d_2;$
 $v_1' = v_1 - d_3;$ and

$$v_6' = v_6 + d_3$$
, where $d_1 = (3(v_3 - v_4)//8)*\delta(|a_{3,0}| \langle QP)$,

$$d_2$$
 = (3(v_3 -v_4)//16)* $\delta(|\,a_{3,0}|\,\langle\,QP)$, and

$$d_3$$
 = (3(v_3 -v_4)//32)* $\delta(|a_{3,0}|\langle QP)$, wherein v_0 - v_7 are initial

boundary pixel values, v_1' - v_6' are adjusted boundary pixel values, $a_{3,0}$ is the discontinuous component of the discrete cosine transform coefficients of a first pixel belonging at the block boundary and QP is a quantization parameter of a macroblock containing v_4 .

- 12. (Previously Presented) The method according to claim 11, wherein the S_0 , S_1 , and S_2 pixels are centered around the block boundary, and wherein corresponding DCT coefficients are determined by an inner product of the DCT kernel and the pixels, S_0 , S_1 , and S_2 .
- 13. (Previously Presented) The method according to claim 1, wherein the S_0 , S_1 and S_2 pixels are a plurality of pixels centered around the block boundary.

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21. (Previously Presented) A method of reducing a blocking artifact appearing when coding a moving picture, comprising:

selecting a plurality of pixels;

obtaining frequency information for each of the plurality of pixels;

adjusting a discontinuous component in a frequency domain of a first pixel of the plurality of pixels based on a corresponding component in the frequency domain of a second pixel of the plurality of pixels; and

applying the adjusting operation to a spatial domain of the first pixel to reduce a blocking artifact.

- 22. (Previously Presented) The method according to claim 21, wherein a magnitude of the discontinuous component in the first pixel is adjusted to a magnitude of the corresponding component in the second pixel, wherein the magnitude of the corresponding component in the second pixel is based on a smallest value of corresponding component magnitudes in remaining pixels of the plurality of pixels.
- 23. (Previously Presented) The method according to claim 22, wherein the adjusting step satisfies at least one of the following conditions:

$$v_{3}' = v_{3} - d$$
; and

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$$v_4' = v_4 + d$$
; where $d = CLIP (c_2(a_{3,0}' - a_{3,0})//c_3, 0, (v_3 - v_4)/2)*\delta(|a_{3,0}| \langle QP),$
$$a_{3,0}' = SIGN(a_{3,0})*MIN(|a_{3,0}|, |a_{3,1}|, |a_{3,2}|), \text{ wherein } v_3 - v_4$$

are initial pixel values, $v_3' - v_4'$ are adjusted pixel values, $a_{3,0} - a_{3,2}$ are the discontinuous component of the discrete cosine transform coefficients of the first and second pixels, c_2 and c_3 are DCT kernel coefficients and QP is a quantization parameter of a macroblock containing v_4 .

24. (Previously Presented) The method according to claim 21, further comprising: determining a smoothness level of the plurality of pixels; and

selecting one of a first and a second mode based on the smoothness level, wherein the blocking artifact is reduced based on the selected mode, wherein the second mode is selected when the following condition is satisfied: $(v_0 = v_1 \& \& v_1 = v_2 \& \& v_2 = v_3 \& \& v_4 = v_5 \& \& v_5 = v_6 \& \& v_6 = v_7)$, wherein $v_0 - v_7$ are pixel values.

25. (Previously Presented) The method according to claim 24, wherein the adjusting step in the second mode satisfies at least one of the following conditions:

$$v_{3}' = v_{3} - d;$$

$$\mathbf{v_4}' = \mathbf{v_4} + \mathbf{d};$$

$$v_2' = v_2 - d_2;$$

$$v_5' = v_5 + d_2;$$

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$$v_1' = v_1 - d_3$$
; and

$$v_6' = v_6 + d_3$$

where

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$$d_1 = (3(v_3 - v_4)//8) * \delta(|a_{3,0}| \langle QP),$$

$$d_2 = (3(v_3 -\! v_4)//16)*\delta(|\, a_{3,0}| \langle QP),$$
 and

$$d_3 = (3(v_3 - v_4)//32)*\delta(|a_{3,0}| \langle QP),$$

wherein v_0 - v_7 are initial pixel values, v_1' - v_6' are adjusted pixel values, $a_{3,0}$ is the discontinuous component of the discrete cosine transform coefficients of the first pixel and QP is a quantization parameter of a macroblock containing v_4 ---

26. (New) An apparatus for reducing a blocking artifact appearing when coding a moving picture, comprising:

means for selecting a plurality of pixels;

means for obtaining frequency information for each of the plurality of pixels;

means for adjusting a discontinuous component in a frequency domain of a first

pixel of the plurality of pixels based on a corresponding component in the frequency domain

of a second pixel of the plurality of pixels; and

means for applying the adjusting operation to a spatial domain of the first pixel to reduce a blocking artifact.